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Branch: Electrical

IInd Mid Term Exam

III year

Paper Code: EE 305

Qns 1 Derive the formulae of steady state error.

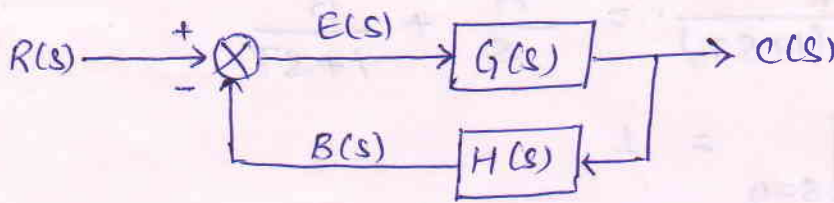
Qns 2 Explain the time response of first order system with unit step input.

Qns 3 Find the range of K for which the system is stable for characteristic equation of feedback control system is

$$5s^3 + Ks^2 + 4s + 1 = 0$$

Solution of Paper
Code EE205

Ans 1



From figure, $B(s) = C(s)H(s)$ and $C(s) = E(s)G(s)$

$$E(s) = R(s) - B(s)$$

$$= R(s) - C(s)H(s)$$

$$E(s) = R(s) - E(s)G(s)H(s)$$

$$E(s)(1 + G(s)H(s)) = R(s)$$

$$E(s) = \frac{R(s)}{1 + G(s)H(s)}$$

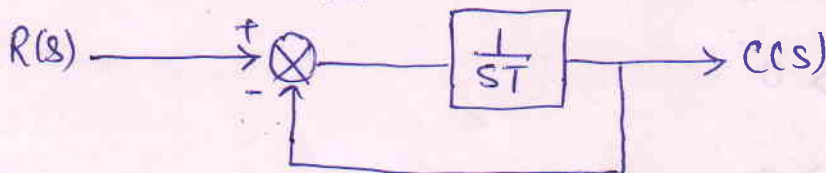
Steady state error is

$$e_{ss} = \lim_{s \rightarrow 0} s E(s)$$

$$e_{ss} = \lim_{s \rightarrow 0} s \frac{R(s)}{1 + G(s)H(s)}$$

Ans 2

Consider a first order system with unity feedback as shown in figure



using closed loop transfer function formulae we get

$$\frac{C(s)}{R(s)} = \frac{\frac{1}{sT}}{1 + \frac{1}{sT}}$$

$$\frac{C(s)}{R(s)} = \frac{1}{1 + sT}$$

$$E(s) = \frac{R(s)}{1 + sT}$$

Since input is unit step function

$$R(s) = \frac{1}{s}$$

$$\therefore C(s) = \frac{1}{s(1+Ts)} = \frac{A}{s} + \frac{B}{1+Ts}$$

$$A = s \cdot \frac{1}{s(1+Ts)} \Big|_{s=0} = 1$$

$$B = (Ts+1) \cdot \frac{1}{s(1+Ts)} \Big|_{s=-\frac{1}{T}} = -T$$

$$C(s) = \frac{1}{s} - \frac{T}{1+Ts}$$

$$C(s) = \frac{1}{s} - \frac{1}{s+\frac{1}{T}}$$

Taking inverse Laplace transform

$$c(t) = 1 - e^{-t/T}$$

Ans 3 Routh's Hurwitz table

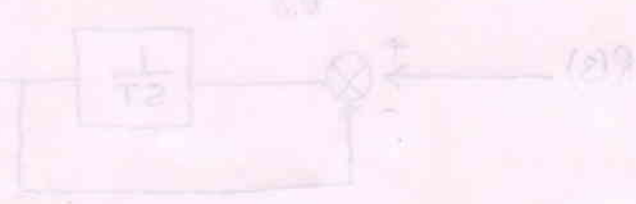
s^3	5	4
s^2	K	1
s^1	$\frac{4K-5}{K}$	
s^0	1	

For stable system:

$$\frac{4K-5}{K} > 0$$

$$4K-5 > 0$$

$$K > \frac{5}{4}$$



$$\frac{1}{Ts} = \frac{C(s)}{R(s)}$$

$$\frac{1}{Ts+1} = \frac{C(s)}{R(s)}$$

$$\frac{C(s)}{R(s)} = \frac{1}{Ts+1}$$